

REAL ALGEBRAIC GEOMETRY LECTURE NOTES
(12 Continued: 26/11/2009)

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THE TARSKI-SEIDENBERG PRINCIPLE

Recall. Let R be a real closed field, $a \in R$. Define

$$\text{sign}(a) := \begin{cases} 1 & \text{if } a > 0, \\ 0 & \text{if } a = 0, \\ -1 & \text{if } a < 0. \end{cases}$$

The Tarski-Seidenberg Principle is the following result.

Theorem 1. Let $f_i(\underline{T}, X) = h_{i,m_i}(\underline{T})X^{m_i} + \dots + h_{i,0}(\underline{T})$ for $i = 1, \dots, s$ be a sequence of polynomials in $n+1$ variables ($\underline{T} = (T_1, \dots, T_n), X$) with coefficients in \mathbb{Z} . Let ϵ be a function from $\{1, \dots, s\}$ to $\{-1, 0, 1\}$. Then there exists a finite boolean combination $B(\underline{T}) := S_1(\underline{T}) \vee \dots \vee S_p(\underline{T})$ of polynomial equations and inequalities in the variables T_1, \dots, T_n with coefficients in \mathbb{Z} such that for every real closed field R and for every $\underline{t} \in R^n$, the system

$$\begin{cases} \text{sign}(f_1(\underline{t}, X)) = \epsilon(1) \\ \vdots \\ \text{sign}(f_s(\underline{t}, X)) = \epsilon(s) \end{cases}$$

has a solution $x \in R$ if and only if $B(\underline{t})$ holds true in R .

Notation I. Let $f_1(X), \dots, f_s(X)$ be a sequence of polynomials in $R[X]$. Let $x_1 < \dots < x_N$ be the roots in R of all f_i that are not identically zero.

Set $x_0 := -\infty$, $x_{N+1} := +\infty$

Remark 1. Let $m := \max(\deg f_i, i = 1, \dots, s)$. Then $N \leq sm$.

Set $I_k :=]x_k, x_{k+1}[$, $k = 0, \dots, N$

Remark 2. $\text{sign}(f_i(x))$ is constant on I_k , for each $i \in 1, \dots, s$, for each $k \in 0, \dots, N$.

Set $sign(f_i(I_k)) := sign(f_i(x))$, $x \in I_k$

Notation II. Let $SIGN_R(f_1, \dots, f_s)$ be the matrix with s rows and $2N + 1$ columns whose i^{th} row (for $i = \{1, \dots, s\}$) is

$$sign(f_i(I_0)), sign(f_i(x_1)), sign(f_i(I_1)), \dots, sign(f_i(x_N)), sign(f_i(I_N)).$$

i.e. $SIGN_R(f_1, \dots, f_s)$ is an $s \times (2N + 1)$ matrix with coefficients in $\{-1, 0, 1\}$ and

$$SIGN_R(f_1, \dots, f_s) := \begin{pmatrix} sign f_1(I_0) & sign f_1(x_1) & \dots & sign f_1(x_N) & sign f_1(I_N) \\ sign f_2(I_0) & sign f_2(x_1) & \dots & sign f_2(x_N) & sign f_2(I_N) \\ \vdots & \vdots & & \vdots & \vdots \\ sign f_s(I_0) & sign f_s(x_1) & \dots & sign f_s(x_N) & sign f_s(I_N) \end{pmatrix}$$

Remark 3. Let $f_1, \dots, f_s \in R[X]$ and $\epsilon : \{1, \dots, s\} \rightarrow \{-1, 0, +1\}$. The system

$$\begin{cases} sign(f_1(X)) = \epsilon(1) \\ \vdots \\ sign(f_s(X)) = \epsilon(s) \end{cases}$$

has a solution $x \in R$ if and only if one column of $SIGN_R(f_1, \dots, f_s)$ is precisely the matrix $\begin{bmatrix} \epsilon(1) \\ \vdots \\ \epsilon(s) \end{bmatrix}$.

Notation III. Let $M_{P \times Q} :=$ the set of $P \times Q$ matrices with coefficients in $\{-1, 0, +1\}$.

Set $W_{s,m} :=$ the disjoint union of $M_{s \times (2l+1)}$, for $l = 0, \dots, sm$.

Notation IV. Let $\epsilon : \{1, \dots, s\} \rightarrow \{-1, 0, 1\}$. Set

$$W(\epsilon) = \left\{ M \in W_{s,m} : \text{one column of } M \text{ is } \begin{bmatrix} \epsilon(1) \\ \vdots \\ \epsilon(s) \end{bmatrix} \right\} \subseteq W_{s,m}$$

Lemma 2. (Reformulation of remark 3 using notation IV) Let $\epsilon : \{1, \dots, s\} \rightarrow \{-1, 0, +1\}$, R real closed field and $f_1(X), \dots, f_s(X) \in R[X]$ of degree $\leq m$. Then the system

$$\begin{cases} \text{sign}(f_1(X)) = \epsilon(1) \\ \vdots \\ \text{sign}(f_s(X)) = \epsilon(s) \end{cases}$$

has a solution $x \in R$ if and only if $SIGN_R(f_1, \dots, f_s) \in W(\epsilon)$.

By Lemma 2 (setting $W' = W(\epsilon)$), we see that the proof of Theorem 1 reduces to showing the following proposition:

Main Proposition 3. Let $f_i(\underline{T}, X) := h_{i,m_i}(\underline{T})X^{m_i} + \dots + h_{i,0}(\underline{T})$ for $i = 1, \dots, s$ be a sequence of polynomials in $n+1$ variables with coefficients in \mathbb{Z} , and let $m := \max\{m_i | i = 1, \dots, s\}$. Let W' be a subset of $W_{s,m}$. Then there exists a boolean combination $B(\underline{T}) = S_1(\underline{T}) \vee \dots \vee S_p(\underline{T})$ of polynomial equations and inequalities in the variables \underline{T} with coefficients in \mathbb{Z} , such that, for every real closed field R and every $\underline{t} \in R^n$, we have

$$SIGN_R(f_1(\underline{t}, X), \dots, f_s(\underline{t}, X)) \in W' \Leftrightarrow B(\underline{t}) \text{ holds true in } R.$$

The proof of the main Proposition will follow by induction from the next main lemma, where we will show that $SIGN_R(f_1, \dots, f_s)$ is completely determined by the “ $SIGN_R$ ” of a (possibly) longer but simpler sequence of polynomials, i.e. $SIGN_R(f_1, \dots, f_{s-1}, f'_s, g_1, \dots, g_s)$, where f'_s = the derivative of f_s , and g_1, \dots, g_s are the remainders of the euclidean division of f_s by $f_1, \dots, f_{s-1}, f'_s$, respectively.

First we will state and prove the lemma and then prove the proposition.