

REAL ALGEBRAIC GEOMETRY LECTURE NOTES
PART II: POSITIVE POLYNOMIALS
(Vorlesung 29b - für 09/02/2023)

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1. APPLICATION OF SPSS TO THE MOMENT PROBLEM (continued)

Lemma 1.1. (Lemma 2.11 of last lecture) Let $L : \mathbb{R}[\underline{X}] \rightarrow \mathbb{R}$ be a linear functional and denote by

$$\tau : \mathbb{N}_0^n \rightarrow \mathbb{R}$$

the corresponding multisequence (i.e. $\tau(\underline{k}) := L(\underline{X}^{\underline{k}}) \forall \underline{k} \in \mathbb{N}_0^n$).

Fix $g \in \mathbb{R}[\underline{X}]$. Then $L(h^2g) \geq 0$ for all $h \in \mathbb{R}[\underline{X}]$ if and only if the multisequence $g(E)_\tau$ is psd.

Proof. Compute:

$$1. L(\underline{X}^{\underline{l}}g) = \sum_{\underline{k} \in \mathbb{Z}_+^n} a_{\underline{k}} \tau(\underline{k} + \underline{l}) = g(E)_\tau(\underline{l}); \text{ for all } \underline{l} \in \mathbb{N}_0^n.$$

Thus if $h = \sum_i c_i \underline{X}^{k_i} \in \mathbb{R}[\underline{X}]$ then $h^2 = \sum_{i,j} c_i c_j \underline{X}^{k_i+k_j}$.

$$2. \text{ So, } L(h^2g) = L\left[\left(\sum_{i,j} c_i c_j \underline{X}^{k_i+k_j}\right)g\right] = \sum_{i,j} c_i c_j L(\underline{X}^{k_i+k_j}g)$$

$$\underbrace{=}_{[\text{by 1.}]} \sum_{i,j} g(E)_\tau(\underline{k}_i + \underline{k}_j) c_i c_j. \quad \square$$

Theorem 1.2. (Schmüdgen's NNSS) (Reformulation in terms of moment sequences) Let $K = K_S$ compact, $S = \{g_1, \dots, g_s\}$ and $\tau : \mathbb{N}_0^n \rightarrow \mathbb{R}$ be a given multisequence. Then τ is a K -moment sequence if and only if the multisequences $(g_1^{e_1} \dots g_s^{e_s})(E)_\tau : \mathbb{N}_0^n \rightarrow \mathbb{R}$ are all psd for all $(e_1, \dots, e_s) \in \{0, 1\}^s$. \square

Next we reformulate question (1) in 2.4 of Lecture 15 in terms of Hankel matrices and bilinear forms.

2. SCHMÜDGEN'S NNSS, HANKEL MATRICES AND BILINEAR FORMS

We want to understand $L(h^2g) \geq 0; h, g \in \mathbb{R}[\underline{X}]$ in terms of Hankel matrices.

Definition 2.1. A real symmetric $n \times n$ matrix A is **psd** if $\underline{x}^T A \underline{x} \geq 0 \forall \underline{x} \in \mathbb{R}^n$. An $\mathbb{N} \times \mathbb{N}$ symmetric matrix (say) A is psd if $\underline{x}^T A \underline{x} \geq 0 \forall \underline{x} \in \mathbb{R}^n$ and $\forall n \in \mathbb{N}$.

Definition 2.2. Let $L \neq 0; L : \mathbb{R}[\underline{X}] \rightarrow \mathbb{R}$ be a given linear functional. Fix $g \in \mathbb{R}[\underline{X}]$. Consider symmetric bilinear form:

$$\begin{aligned} \langle \cdot, \cdot \rangle_g : \mathbb{R}[\underline{X}] \times \mathbb{R}[\underline{X}] &\rightarrow \mathbb{R} \\ \langle h, k \rangle_g &:= L(hkg); h, k \in \mathbb{R}[\underline{X}] \end{aligned}$$

Denote by S_g the $\mathbb{N} \times \mathbb{N}$ real symmetric matrix with $\underline{\alpha}\underline{\beta}$ -entry $\langle \underline{X}^{\underline{\alpha}}, \underline{X}^{\underline{\beta}} \rangle_g \forall \underline{\alpha}, \underline{\beta} \in \mathbb{N}_0^n$, i.e. the $\underline{\alpha}\underline{\beta}$ -entry of S_g is $L(\underline{X}^{\underline{\alpha}+\underline{\beta}} g)$.

Example. Let $g = 1$, then

$$\langle \underline{X}^{\underline{\alpha}}, \underline{X}^{\underline{\beta}} \rangle_1 = L(\underline{X}^{\underline{\alpha}+\underline{\beta}}) := s_{\underline{\alpha}+\underline{\beta}}.$$

More generally, if $g = \sum a_\gamma \underline{X}^\gamma$ then

$$\langle \underline{X}^{\underline{\alpha}}, \underline{X}^{\underline{\beta}} \rangle_g = L\left(\sum_\gamma a_\gamma \underline{X}^{\underline{\alpha}+\underline{\beta}+\underline{\gamma}}\right) = \sum_{\underline{\gamma}} a_{\underline{\gamma}} s_{\underline{\alpha}+\underline{\beta}+\underline{\gamma}}.$$

Proposition 2.3. Let L, g be fixed as above. Then the following are equivalent:

1. $L(\sigma g) \geq 0 \forall \sigma \in \sum \mathbb{R}[\underline{X}]^2$.
2. $L(h^2g) \geq 0 \forall h \in \mathbb{R}[\underline{X}]$.
3. $\langle \cdot, \cdot \rangle_g$ is psd (i.e. $\langle h, h \rangle_g \geq 0$ for all $h \in \mathbb{R}[\underline{X}]^2$).
4. S_g is psd.

Proof. (1) \Leftrightarrow (2) is clear.

Since $\langle h, h \rangle_g = L(h^2g)$, (2) \Leftrightarrow (3) is clear.

(3) \Leftrightarrow (4) is also clear. \square

2.4. Example. (Hamburger) Let $n = 1$. A linear functional $L : \mathbb{R}[X] \rightarrow \mathbb{R}$ comes from a Borel measure on \mathbb{R} if and only if $L(\sigma) \geq 0$ for every $\sigma \in \sum \mathbb{R}[X]^2$.

Proof. From Haviland we know L comes from a Borel measure iff $L(f) \geq 0$ for every $f(X) \in \mathbb{R}[X], f \geq 0$ on \mathbb{R} . But $\text{Psd}(\mathbb{R}) = \sum \mathbb{R}[X]^2$ (by exercise in Real Algebraic Geometry course in WS 2009-10). So the condition is clear. \square

Remark 2.5. We can express Hamburgers's Theorem via Hankel matrix S_g with $g = 1$ the constant polynomial since $n = 1$, so (for $i, j \in \mathbb{N}$) the ij th coefficient of S_1 is $s_{i+j} = L(X^{i+j})$.

Hence, $S_1 = \begin{pmatrix} s_0 & s_1 & s_2 & \dots \\ s_1 & s_2 & \dots & \\ s_2 & \dots & \ddots & \\ \dots & \dots & & \end{pmatrix}$ is psd.

END OF RAG I IN WISE 2022/2023

2.1. REFORMULATION OF SCHMÜDGEN'S SOLUTION TO THE MOMENT PROBLEM IN TERMS OF HANKEL MATRICES

2.6. Let $S = \{g_1, \dots, g_s\} \subseteq \mathbb{R}[X]$ and $K_S \subseteq \mathbb{R}^n$ is compact. A linear functional L on $\mathbb{R}[X]$ is represented by a Borel measure on K iff the $2^S \mathbb{N} \times \mathbb{N}$ Hankel matrices $\{S_{g_1^{e_1} \dots g_s^{e_s}} | (e_1, \dots, e_s) \in \{0, 1\}^s\}$ are psd, where $S_g := [L(X^{\underline{\alpha} + \underline{\beta}} g)]_{\underline{\alpha}, \underline{\beta}} ; \underline{\alpha}, \underline{\beta} \in \mathbb{N}^n$.

3. FINITE SOLVABILITY OF THE K - MOMENT PROBLEM

Definition 3.1. Let K be a basic closed semi-algebraic subset of \mathbb{R}^n .

1. The K -moment problem (**KMP**) is **finitely solvable** if there exists S finite, $S \subseteq \mathbb{R}[X]$ such that:
 - (i) $K = K_S$, and
 - (ii) \forall linear functional L on $\mathbb{R}[X]$ we have: $L(T_S) \geq 0 \Rightarrow L(\text{Psd}(K)) \geq 0$
(equivalently, (iii) $L(T_S) \geq 0 \Rightarrow \exists \mu : L = \int d\mu$).
2. We shall say S **solves the KMP** if (i) and (ii) (equivalently (i) and (iii)) hold.

3.2. Schmüdgen's solution to the KPM for K compact b.c.s.a. Let $K \subseteq \mathbb{R}^n$ be a compact basic closed semi-algebraic set. Then S solves the KMP for any finite description S of K (i.e. for all finite $S \subseteq \mathbb{R}[\underline{X}]$ with $K = K_S$).

One can restate the condition “ S solves the K -Moment problem” via the equality of two preorderings. We shall adopt this approach throughout:

Definition 3.3. Let $T_S \subseteq \mathbb{R}[\underline{X}]$ be a preordering. Define the **dual cone** of T_S :

$$T_S^v := \{L \mid L : \mathbb{R}[\underline{X}] \rightarrow \mathbb{R} \text{ is a linear functional; } L(T_S) \geq 0\},$$

and the **double dual cone**:

$$T_S^{vv} := \{f \mid f \in \mathbb{R}[\underline{X}]; L(f) \geq 0 \forall L \in T_S^v\}.$$

Lemma 3.4. For $S \subseteq \mathbb{R}[\underline{X}]$, S finite:

- (a) $T_S \subseteq T_S^{vv}$
- (b) $T_S^{vv} \subseteq \text{Psd}(K_S)$.

Proof. (a) Immediate by definition.

- (b) Let $f \in T_S^{vv}$. To show: $f(\underline{x}) \geq 0 \forall \underline{x} \in K_S$.

Now every $\underline{x} \in \mathbb{R}^n$ determines an \mathbb{R} -algebra homomorphism

$$e_{v_x} := L_{\underline{x}} \in \text{Hom}(\mathbb{R}[\underline{X}], \mathbb{R}); L_{\underline{x}}(g) = e_{v_x}(g) := g(\underline{x}) \forall g \in \mathbb{R}[\underline{X}],$$

this $L_{\underline{x}}$ is in particular a linear functional.

Moreover we claim that $L_{\underline{x}}(T_S) \geq 0$ for $\underline{x} \in K_S$. Indeed if $g \in T_S$ then $L_{\underline{x}}(g) = g(\underline{x}) \geq 0$ for $\underline{x} \in K_S$.

So, by assumption on f we must also have $L_{\underline{x}}(f) \geq 0$ for $\underline{x} \in K_S$, i.e. $f(\underline{x}) \geq 0$ for all $\underline{x} \in K_S$ as required. □

We summarize as follows:

Corollary 3.5. For finite $S \subseteq \mathbb{R}[\underline{X}]$:

$$T_S \subseteq T_S^{vv} \subseteq \text{Psd}(K_S).$$

Corollary 3.6. (Reformulation of finite solvability) Let $K \subseteq \mathbb{R}^n$ be a b.c.s.a. set and $S \subseteq \mathbb{R}[\underline{X}]$ be finite. Then S solves the KMP iff

(j) $K = K_S$, and

(jj) $T_S^{\text{vv}} = \text{Psd}(K)$.

Proof. Assume (ii) of definition 3.1, i.e. $\forall L : L(T_S) \geq 0 \Rightarrow L(\text{Psd}(K)) \geq 0$, and show (jj) i.e. $T_S^{\text{vv}} = \text{Psd}(K)$:

Let $f \in \text{Psd}(K)$. Show $f \in T_S^{\text{vv}}$ i.e. show $L(f) \geq 0 \forall L \in T_S^{\text{v}}$.

Assume $L(T_S) \geq 0$. Then by assumption $L(\text{Psd}(K)) \geq 0$. So, $L(f) \geq 0$ as required.

Conversely, assume (jj) and show (ii):

Let $L(T_S) \geq 0$, i.e. $L \in T_S^{\text{v}}$. Show $L(\text{Psd}(K)) \geq 0$, i.e show $L(f) \geq 0 \forall f \in \text{Psd}(K)$.

Now [by assumption (jj)] $f \in \text{Psd}(K) \Rightarrow f \in T_S^{\text{vv}} \Rightarrow L(f) \geq 0 \forall L \in T_S^{\text{v}}$. \square

We shall come back later to T_S^{vv} and describe it as closure w.r.t. an appropriate topology.

4. HAVILAND'S THEOREM

For the proof of Haviland's theorem (2.5 of lecture 15), we will recall Riesz Representation Theorem.

Definition 4.1. A topological space is said to be **Hausdorff** (or **seperated**) if it satisfies

(H4): any two distinct points have disjoint neighbourhoods, or

(T₂): two distinct points always lie in disjoint open sets.

Definition 4.2. A topological space χ is said to be **locally compact** if $\forall x \in \chi \exists$ an open neighbourhood $\mathcal{U} \ni x$ such that $\overline{\mathcal{U}}$ is compact.

Theorem 4.3. (Riesz Representation Theorem) Let χ be a locally compact Hausdorff space and $L : \text{Cont}_c(\chi, \mathbb{R}) \rightarrow \mathbb{R}$ be a positive linear functional i.e. $L(f) \geq 0 \forall f \geq 0$ on χ . Then there exists a unique (positive regular) Borel measure μ on χ such that $L(f) = \int_{\chi} f d\mu \forall f \in \text{Cont}_c(\chi, \mathbb{R})$, where $\text{Cont}_c(\chi, \mathbb{R}) :=$

the ring (\mathbb{R} -algebra) of all continuous functions $f : \chi \rightarrow \mathbb{R}$ (addition and multiplication defined pointwise) with compact support i.e. such that the set $\text{supp}(f) := \{x \in \chi : f(x) \neq 0\}$ is compact.

Definition 4.4. L **positive** means:

$$L(f) \geq 0 \forall f \in \text{Cont}_c(\chi, \mathbb{R}) \text{ with } f \geq 0 \text{ on } \chi.$$