## REAL ALGEBRAIC GEOMETRY LECTURE NOTES (12 Continued: 26/11/2009 - BEARBEITET 1/12/2022)

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## THE TARSKI-SEIDENBERG PRINCIPLE

**Recall.** Let R be a real closed field,  $a \in R$ . Define

$$sign(a) := \begin{cases} 1 & \text{if } a > 0, \\ 0 & \text{if } a = 0, \\ -1 & \text{if } a < 0. \end{cases}$$

The Tarski-Seidenberg Principle is the following result.

**Theorem 1.** Let  $f_i(\underline{T}, X) = h_{i,m_i}(\underline{T})X^{m_i} + \ldots + h_{i,0}(\underline{T})$  for  $i = 1, \ldots, s$ be a sequence of polynomials in n + 1 variables  $(\underline{T} = (T_1, \ldots, T_n), X)$  with coefficients in  $\mathbb{Z}$ . Let  $\epsilon$  be a function from  $\{1, \ldots, s\}$  to  $\{-1, 0, 1\}$ . Then there exists a finite boolean combination  $B(\underline{T}) := S_1(\underline{T}) \vee \ldots \vee S_p(\underline{T})$  of polynomial equations and inequalities in the variables  $T_1, \ldots, T_n$  with coefficients in  $\mathbb{Z}$ such that for every real closed field R and for every  $\underline{t} \in \mathbb{R}^n$ , the system

$$\begin{cases} sign(f_1(\underline{t}, X)) = \epsilon(1) \\ \vdots \\ sign(f_s(\underline{t}, X)) = \epsilon(s) \end{cases}$$

has a solution  $x \in R$  if and only if  $B(\underline{t})$  holds true in R.

**Notation I.** Let  $f_1(X), \ldots, f_s(X)$  be a sequence of polynomials in R[X]. Let  $x_1 < \ldots < x_N$  be the roots in R of all  $f_i$  that are not identically zero. Set  $x_0 := -\infty$ ,  $x_{N+1} := +\infty$ 

**Remark 1.** Let  $m := max(degf_i, i = 1, ..., s)$ . Then  $N \le sm$ . Set  $I_k := ]x_k, x_{k+1}[$ , k = 0, ..., N**Remark 2.**  $sign(f_i(x))$  is constant on  $I_k$ , for each  $i \in \{1, ..., s\}$ , for each  $k \in \{0, ..., N\}$ .  $REAL \; ALGEBRAIC \; GEOMETRY \; LECTURE \; NOTES$ 

Set  $sign(f_i(I_k)) := sign(f_i(x)), x \in I_k$ 

**Notation II.** Let  $SIGN_R(f_1, \ldots, f_s)$  be the matrix with s rows and 2N + 1 columns whose  $i^{th}$  row (for  $i = \{1, \ldots, s\}$ ) is

$$sign(f_i(I_0)), sign(f_i(x_1)), sign(f_i(I_1)), \ldots, sign(f_i(x_N)), sign(f_i(I_N)).$$

i.e.  $SIGN_R(f_1, \ldots, f_s)$  is the  $s \times (2N+1)$  matrix with coefficients in  $\{-1, 0, 1\}$  defined as

$$SIGN_{R}(f_{1},...,f_{s}) := \begin{pmatrix} signf_{1}(I_{0}) & signf_{1}(x_{1}) & \dots & signf_{1}(x_{N}) & signf_{1}(I_{N}) \\ signf_{2}(I_{0}) & signf_{2}(x_{1}) & \dots & signf_{2}(x_{N}) & signf_{2}(I_{N}) \\ \vdots & \vdots & \vdots & \vdots \\ signf_{s}(I_{0}) & signf_{s}(x_{1}) & \dots & signf_{s}(x_{N}) & signf_{s}(I_{N}) \end{pmatrix}$$

**Remark 3.** Let  $f_1, \ldots, f_s \in R[X]$  and  $\epsilon : \{1, \ldots, s\} \rightarrow \{-1, 0, 1\}$ . The system

$$\begin{cases} sign(f_1(X)) = \epsilon(1) \\ \vdots \\ sign(f_s(X)) = \epsilon(s) \end{cases}$$

has a solution  $x \in R$  if and only if one column of  $SIGN_R(f_1, \ldots, f_s)$  is precisely the matrix  $\begin{bmatrix} \epsilon(1) \\ \vdots \\ \epsilon(s) \end{bmatrix}$ .

Notation III. Let  $M_{P \times Q}$  := the set of  $P \times Q$  matrices with coefficients in  $\{-1, 0, +1\}$ .

Set  $W_{s,m}$  := the disjoint union of  $M_{s \times (2l+1)}$ , for  $l = 0, \ldots, sm$ .

Notation IV. Let  $\epsilon : \{1, \ldots, s\} \rightarrow \{-1, 0, 1\}$ . Set

$$W(\epsilon) = \{ M \in W_{s,m} : one \ column \ of \ M \ is \ \begin{bmatrix} \epsilon(1) \\ \vdots \\ \epsilon(s) \end{bmatrix} \} \subseteq W_{s,m}$$

Lemma 2. (Reformulation of Remark 3 using notation IV)

Let  $\epsilon : \{1, \ldots, s\} \to \{-1, 0, 1\}, R$  real closed field and  $f_1(X), \ldots, f_s(X) \in R[X]$  of degree  $\leq m$ . Then the system

$$\begin{cases} sign(f_1(X)) = \epsilon(1) \\ \vdots \\ sign(f_s(X)) = \epsilon(s) \end{cases}$$

has a solution  $x \in R$  if and only if  $SIGN_R(f_1, \ldots, f_s) \in W(\epsilon)$ .

By Lemma 2 (setting  $W' = W(\epsilon)$ ), we see that the proof of Theorem 1 reduces to showing the following proposition:

**Main Proposition 3.** Let  $f_i(\underline{T}, X) := h_{i,m_i}(\underline{T})X^{m_i} + \ldots + h_{i,0}(\underline{T})$  for  $i = 1, \ldots, s$  be a sequence of polynomials in n + 1 variables with coefficients in  $\mathbb{Z}$ , and let  $m := max\{m_i | i = 1, \ldots, s\}$ . Let W' be a subset of  $W_{s,m}$ . Then there exists a boolean combination  $B(\underline{T}) = S_1(\underline{T}) \vee \ldots \vee S_p(\underline{T})$  of polynomial equations and inequalities in the variables  $\underline{T}$  with coefficients in  $\mathbb{Z}$ , such that, for every real closed field R and every  $\underline{t} \in \mathbb{R}^n$ , we have

 $SIGN_R(f_1(\underline{t}, X), \dots, f_s(\underline{t}, X) \in W' \Leftrightarrow B(\underline{t})$  holds true in R.

The proof of the main Proposition will follow by induction from the next main lemma, where we will show that  $SIGN_R(f_1, \ldots, f_s)$  is completely determined by the " $SIGN_R$ " of a (possibly) longer but simpler sequence of polynomials, i.e.  $SIGN_R(f_1, \ldots, f_{s-1}, f'_s, g_1, \ldots, g_s)$ , where  $f'_s =$  the derivative of  $f_s$ , and  $g_1, \ldots, g_s$  are the remainders of the euclidean division of  $f_s$  by  $f_1, \ldots, f_{s-1}, f'_s$ , respectively.

First we will state and prove the main lemma and then prove the main proposition.